



1 Multidimensional linear problem with constraints

A multidimensional linear problem, also known as a linear programming problem, involves optimizing a linear objective function subject to linear constraints. These problems are prevalent in various fields such as operations research, economics, engineering, and finance.

Here's how you can implement this in MATLAB:

1.1 Command "linprog"

To solve a multidimensional linear problem with constraints in MATLAB, you can use the built-in function `linprog`. This function is designed to solve linear programming problems of the form:

Minimize:
 $f(x) = c^T x$
Subject to:
 $Ax \leq b$
 $lb \leq x \leq ub$

Here's how you can use `linprog` for your problem:

```
% Define the objective function coefficients  
c = [1; 2; 3]; % Coefficients of the objective function  
% Define the inequality constraints: A*x <= b  
A = [1, 1, 1; % Coefficients of the first constraint  
     2, 3, 1]; % Coefficients of the second constraint  
b = [10; 20]; % Right-hand side of the constraints  
% Define the bounds for variables: lb <= x <= ub  
lb = zeros(3,1); % Lower bounds for variables  
ub = []; % Upper bounds for variables (empty for unbounded)
```

```

% Solve the linear programming problem
[x, fval, exitflag] = linprog(c, [], [], A, b, lb, ub);
% Display the results
if exitflag == 1
    disp('Optimal solution found:');
    disp(['x = ', num2str(x)]);
    disp(['Optimal objective value = ', num2str(fval)]);
else
    disp('Optimal solution not found.');
```

Example 1 Let consider the function $f(x) = x_1 + 2x_2 + 3x_3$ subject to the following constraints:

$$\begin{aligned} x_1 + x_2 + x_3 &\leq 15 \\ 2x_1 + 3x_2 + x_3 &\leq 25 \\ x_1, x_2, x_3 &\geq 0 \end{aligned}$$

Here's how you can solve this problem using linprog in MATLAB:

```

c = [1; 2; 3];
A = [1, 1, 1;
     2, 3, 1];
b = [15; 25];
lb = zeros(3,1);
ub = [];
[x, fval, exitflag] = linprog(c, [], [], A, b, lb, ub);
if exitflag == 1
    disp('Optimal solution found:');
    disp(['x = ', num2str(x)]);
    disp(['Optimal objective value = ', num2str(fval)]);
else
    disp('Optimal solution not found.');
```

2 Multidimensional non-linear problem with constraints

2.1 Command "fmincon"

To solve a multidimensional non-linear problem with constraints in MATLAB, you can use the fmincon function. fmincon is a versatile optimization function capable of handling nonlinear constraints. Here's a basic example demonstrating how to use fmincon:

$$f(x) = (x_1 - 2)^2 + (x_2 - 3)^2$$

Subject to the following constraints:

$$x_1 + x_2 \leq 5$$

$$x_1 - x_2 \geq 2$$

$$x_1, x_2 \geq 0$$

Here's how you can implement this in MATLAB using `fmincon`:

```
% Define the objective function
fun = @(x) (x(1) - 2)^2 + (x(2) - 3)^2;
% Initial guess for x
x0 = [0; 0];
% Define the nonlinear inequality constraints
nonlcon = @(x) constraints(x);
% Solve the optimization problem
[x, fval, exitflag, output] = fmincon(fun, x0, [], [], [], [], [], [], nonlcon);
% Display the results
if exitflag > 0
    disp('Optimal solution found:');
    disp(['x = ', num2str(x)]);
    disp(['Optimal objective value = ', num2str(fval)]);
else
    disp('Optimal solution not found.');
end
% Define the nonlinear inequality constraints
function [c, ceq] = constraints(x)
    c = [x(1) + x(2) - 5; % x1 + x2 <= 5
        -(x(1) - x(2) - 2)]; % x1 - x2 >= 2
    ceq = []; % No equality constraints
end
```

Suppose we want to minimize the following function:

$$f(x)$$

Subject to the following constraints:

$$g(x) = 4$$

$$h(x) \geq 1$$

$$x = (x_1, x_2) \text{ with } x_1, x_2 \geq 0$$

Here's how you can implement this in MATLAB using `fmincon`:

```
fun = @(x) f(x);
x0 = [0; 0];
nonlcon = @(x) constraints(x);
Aeq = [1, 1];
beq = 4;
[x, fval, exitflag, output] = fmincon(fun, x0, [], [], Aeq, beq, [], [], nonlcon);
if exitflag > 0
    disp('Optimal solution found:');
    disp(['x = ', num2str(x)]);
    disp(['Optimal objective value = ', num2str(fval)]);
else
    disp('Optimal solution not found.');
end
```

```

function [c, ceq] = constraints(x)
    c = -(g(x) - 1); % g(x) >= 1
    ceq = []; % No equality constraints
end

```

Find the minimum value of Rosenbrock's function when there is a linear inequality constraint.

Find the minimum value starting from the point $[-1, 2]$, constrained to have $x(1) + 2x(2) \leq 1$.

Express this constraint in the form $Ax \leq b$ by taking $A = [1, 2]$ and $b = 1$.

Here's how you can implement this in MATLAB using `fmincon`:

```

fun = @(x)100*(x(2)-x(1)^2)^2 + (1-x(1))^2;
x0 = [-1,2];
A = [1,2];
b = 1;
x = fmincon(fun,x0,A,b)

```

Find the minimum value of Rosenbrock's function when there are both a linear inequality constraint and a linear equality constraint.

Set the objective function `fun` to be Rosenbrock's function.

Find the minimum value starting from the point $[0.5, 0]$, constrained to have $x(1) + 2x(2) \leq 1$ and $2x(1) + x(2) = 1$.

Here's how you can implement this in MATLAB using `fmincon`:

```

fun = @(x)100*(x(2)-x(1)^2)^2 + (1-x(1))^2;
x0 = [0.5,0];
A = [1,2];
b = 1;
Aeq = [2,1];
beq = 1;
x = fmincon(fun,x0,A,b,Aeq,beq)

```