

% TP N°4 Numerical methods:
 Dr. Rezzoug Imad
 % Partial Differential Equations
 % Finite-Difference Method for Parabolic PDEs: Heat equation

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clc;
clear all;
close all;
%Input
f_fun = input('\n Input Function f=u(x,0) = ','s');
f=inline(f_fun,'x');
c1 = input('\n Enter c1=u(0,t) = ');
c2 = input('\n Enter c2=u(a,t) = ');
a = input('\n Enter right pt. of [0,a] = ');
b = input('\n Enter right pt. of [0,b] = ');
c = input('\n Enter the constant in the heat eqn. (c)= ');
n = input ('\n Enter No. of grid pts. over [0,a] (n)= ');
m = input ('\n Enter No. of grid pts. over [0,b] (m)= ');
%Initialize parameters
h=a/(n-1);
k=b/(m-1);
r=c*k/h;
s=1-2*r;
U=zeros(n,m);
%Boundary conditions
U(1,1:m)=c1;
U(n,1:m)=c2;
%Generate first row
U(2:n-1,1)=feval(f,h:h:(n-2)*h);
%Generate remaining rows of U
for j=2:m
    for i=2:n-1
        U(i,j)=s*U(i,j-1)+r*(U(i-1,j-1)+U(i+1,j-1));
    end
end
U=U'
% Plotting the Approximate solution of the PDE.
t=0:h:a ; x=0:k:b; mesh(t,x,U)

```

% TP N°6 Numerical methods:
 Dr. Rezzoug Imad
 % Partial Differential Equations
 % Finite-Difference Method for Hyperbolic PDEs: Wave equation

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clc;
clear all;
close all;
%Input
f_fun = input('\n Input Function f=u(x,0) = ','s');
f=inline(f_fun,'x');
g_fun = input('\n Input Function g=u_t(x,0) = ','s');
g=inline(g_fun,'x');
a = input('\n Enter right pt. of [0,a] = ');
b = input('\n Enter right pt. of [0,b] = ');
c = input('\n Enter the constant in the wave eqn. (c)= ');
n = input ('\n Enter No. of grid pts. over [0,a], (n) = ');
m = input ('\n Enter No. of grid pts. over [0,b], (m) = ');
%Initialize parameters
h=a/(n-1);
k=b/(m-1);
r=c*k/h;
r2=r^2;
r22=r^2/2;
s1=1-r^2;
s2=2-2*r^2;
U=zeros(n,m);
%Generate first and second rows
for i=2:n-1
    U(i,1)=feval(f,h*(i-1));
    U(i,2)=s1*feval(f,h*(i-1))+k*feval(g,h*(i-1))+r22*(feval(f,h*i)+feval(f,h*(i-2)));
end
%Generate remaining rows of U
for j=3:m
    for i=2:(n-1)
        U(i,j)=s2*U(i,j-1)+r2*(U(i-1,j-1)+U(i+1,j-1))-U(i,j-2);
    end
end
U=U'
% Plotting the Approximate solution of the PDE.
t=0:h:a ; x=0:k:b; mesh(t,x,U)

```

% **TP N°5** Numerical methods:

Dr. Rezzoug Imad

% Partial Differential Equations

% Finite-Difference Method for Parabolic PDEs: **Heat equation**

% **Crank-Nicholson Method**

clc;

clear all;

close all;

%Input

f_fun = input('\n Input Function f=u(x,0) = ','s');

f=inline(f_fun,'x');

c1 = input('\n Enter c1=u(0,t) = ');

c2 = input('\n Enter c2=u(a,t) = ');

a = input('\n Enter right pt. of [0,a] = ');

b = input('\n Enter right pt. of [0,b] = ');

c = input('\n Enter the constant in the heat eqn. (c)= ');

n = input ('\n Enter No. of grid pts. over [0,a] (n)= ');

m = input ('\n Enter No. of grid pts. over [0,b] (m)= ');

%Initialize parameters

h=a/(n-1);

k=b/(m-1);

r=c^2*k/h^2;

s1=2+2/r;

s2=2/r-2;

U=zeros(n,m);

%Boundary conditions

U(1,1:m)=c1;

U(n,1:m)=c2;

%Generate first row

U(2:n-1,1)=feval(f,h:h:(n-2)*h);

%Form and solve tridiagonal system AX=B

Vd(1,1:n)=s1*ones(1,n);

Vd(1)=1;

Vd(n)=1;

Va=-ones(1,n-1);

Va(n-1)=0;

Vc=-ones(1,n-1);

Vc(1)=0;

Vb(1)=c1;

Vb(n)=c2;

for j=2:m

for i=2:n-1

Vb(i)=U(i-1,j-1)+U(i+1,j-1)+s2*U(i,j-1);

end

X=trisys(Va,Vd,Vc,Vb);

U(1:n,j)=X';

end

U=U'

% Plotting the Approximate solution of the PDE.

t=0:h:a ; x=0:k:b; mesh(t,x,U)

% **TP N°5** Numerical methods:

Dr. Rezzoug Imad

% Partial Differential Equations

function X = trisys(A,D,C,B)

%TRISYS Solution of a triangular linear system.

% It is assumed that D and B have dimension n,

% and that A and C have dimension n-1;

% Sample call

% X = trisys(A,D,C,B)

% Inputs

% A sub diagonal vector

% D diagonal vector

% C super diagonal vector

% B right hand side vector

% Return

% X solution vector

%

% NUMERICAL METHODS: MATLAB Programs, (c) John H. Mathews
1995

% To accompany the text:

% NUMERICAL METHODS for Mathematics, Science and Engineering,
2nd Ed, 1992

% Prentice Hall, Englewood Cliffs, New Jersey, 07632, U.S.A.

% Prentice Hall, Inc.; USA, Canada, Mexico ISBN 0-13-624990-6

% Prentice Hall, International Editions: ISBN 0-13-625047-5

% This free software is compliments of the author.

% E-mail address: in%"mathews@fullerton.edu"

%

% Algorithm 9.10. (Finite-Difference Method).

% Section 9.9, Finite-Difference Method, Page 496

n = length(B);

for k = 2:n,

mult = A(k-1)/D(k-1);

D(k) = D(k) - mult*C(k-1);

B(k) = B(k) - mult*B(k-1);

end

X(n) = B(n)/D(n);

for k = (n-1):-1:1,

X(k) = (B(k) - C(k)*X(k+1))/D(k);

end