

Series 2

Ex 1 :

All the acceleration of this motion in each interval.

* at $[0-10s]$:

$$a = \frac{\Delta v}{\Delta t} = \frac{5-0}{10-0} = \frac{1}{2} = 0,5 \text{ m/s}^2 = \text{cst} \Rightarrow$$

الحركة المستقيمة متغيرة بانتظام

* nature of the movement is : **Uniformly Varied Rectilinear**

motion or **rectilinear motion with uniformly accelerated**

accelerated motion $v > 0$ and $a > 0$
 $\vec{v} \cdot \vec{a} > 0$

* at $t = [10-30s]$: $v = 5 \text{ m/s} = \text{cst}$

$$\Rightarrow a = 0 \text{ m/s}^2$$

الحركة المستقيمة منتظمة

* nature of the movement is : **Uniform rectilinear motion**

* at $t = [30-40s]$: $a = \frac{\Delta v}{\Delta t} = \frac{0-5}{40-30} = \frac{-5}{10} = -0,5 \text{ m/s}^2 < 0$

$a = \text{cst} < 0 \Rightarrow$ **Uniformly Varied rectilinear**
الحركة المستقيمة متغيرة بانتظام

M^{VF} décéléré $\equiv$ decelerated movement

Ex2: movement $\Delta D \Rightarrow$ straight = rectilinear

$$a = 8t + 1 \text{ (m/s}^2\text{)} \Rightarrow a = f(t).$$

1/ the velocity of this movement at $t=0, v=2 \text{ (m/s)}$

$$a = \frac{dv}{dt} \Rightarrow dv = a \cdot dt$$

معدل التغير في السرعة v يجب أن يكون متعلقاً بـ a

$$\int_{v_0}^v dv = \int_{t_0}^t \underbrace{(8t+1)}_a dt \Rightarrow \left. v \right|_{v_0}^v = \left. \frac{8t^2}{2} + t \right|_{t_0=0}^t$$

$$v - v_0 = \frac{8t^2}{2} + t \Rightarrow v = \frac{8t^2}{2} + t + v_0 \quad \text{we have } \begin{cases} \text{at } t=0 \\ v = 2 \text{ m/s} \end{cases}$$

$$\Rightarrow 2 = \frac{8(0)^2}{2} + 0 + v_0 \Rightarrow \boxed{v_0 = 2 \text{ (m/s)}} \quad \textcircled{2}$$

$$\textcircled{2} \rightarrow \textcircled{1} \Rightarrow \boxed{v = \frac{8t^2}{2} + t + 2} \text{ (m/s)} \quad \textcircled{*}$$

2/ the time equation of this movement at $t=0\text{s}, x=0\text{m}$

$$v = \frac{dx}{dt} \Rightarrow dx = v dt \Rightarrow \int_{x_0}^x dx = \int_{t_0}^t \underbrace{\left(\frac{8t^2}{2} + t + 2 \right)}_v dt$$

$$\left. x \right|_{x_0}^x = \left. \frac{8t^3}{6} + \frac{t^2}{2} + 2t \right|_{t_0=0}^{t_0}$$

$$x - x_0 = \frac{8t^3}{6} + \frac{t^2}{2} + 2t \Rightarrow x = \frac{8t^3}{6} + \frac{t^2}{2} + 2t + x_0$$

$$\Rightarrow 0 = 0 + x_0 \Rightarrow \boxed{x_0 = 0 \text{ m}}$$

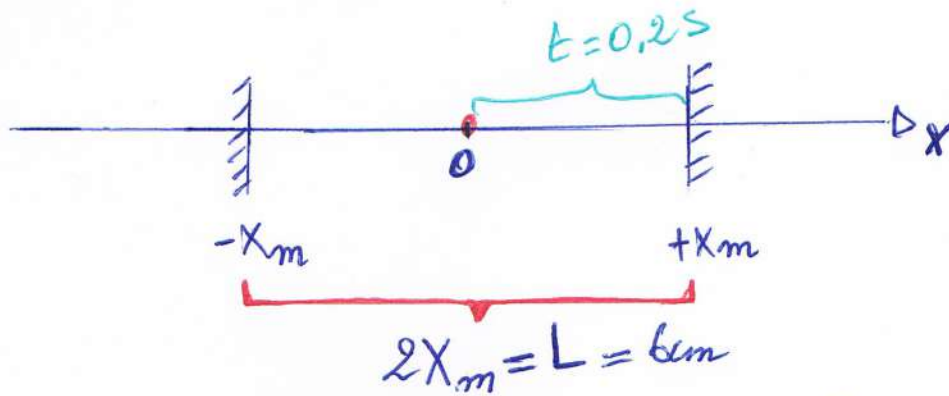
$$x = \frac{8t^3}{6} + \frac{t^2}{2} + 2t$$

3/ the nature of this movement is Rectilinear motion
with variable acceleration because $a = f(t)$

Series 2

Ex 3: $x(t) = X_m \cos(\omega t + \phi)$

- Maximum elongation X_m ??



we have $2X_m = L = 6\text{cm} \Rightarrow X_m = \frac{6}{2} = 3\text{cm} \Rightarrow \boxed{X_m = 3\text{cm}}$

- Period T:

we have: $T = 4t = 4(0,2) = 0,8\text{s} \Rightarrow \boxed{T = 0,8\text{s}}$

- Pulsation ω : $\omega = \frac{2\pi}{T} \Rightarrow \omega = \frac{2\pi}{0,8} \Rightarrow \boxed{\omega = 2,5\pi \text{ (rad/s)}}$

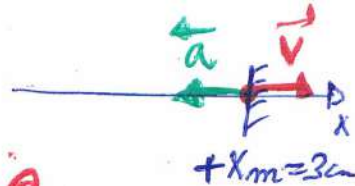
- frequency f : $f = \frac{1}{T} \Rightarrow f = \frac{1}{0,8} \Rightarrow \boxed{f = 1,25\text{Hz}}$

- phase initiale ϕ : from the initial conditions at

$t=0 \begin{cases} x=0 \\ v=3\text{(m/s)} > 0 \end{cases}$ mobile is at the origin

$x(t) = X_m \cos(\omega t + \phi) \Rightarrow x(t) = \overset{\text{cm}}{3} \cos(2,5\pi t + \phi) \text{ (cm)}$

$$\Rightarrow \begin{cases} x(t) = 3 \cos(2.5\pi t + \phi) \text{ (cm)} \\ v(t) = -3(2.5\pi) \sin(2.5\pi t + \phi) > 0 \end{cases}$$



$$\Rightarrow \text{at } t=0 \Rightarrow \begin{cases} 0 = 3 \cos(2.5\pi(0) + \phi) \\ v = -3(2.5\pi) \sin(2.5\pi(0) + \phi) > 0 \end{cases}$$

$$\Rightarrow \begin{cases} 3 \cos \phi = 0 \\ -7.5\pi \sin \phi > 0 \end{cases} \Rightarrow \begin{cases} 3 \cos \phi = 0 \\ 7.5\pi \sin \phi < 0 \end{cases} \Rightarrow$$

$$\boxed{\phi = -\frac{\pi}{2}} \text{ phase initiale}$$

$$\Rightarrow x(t) = 3 \cos(2.5\pi t - \frac{\pi}{2})$$

2/ the time ~~t??~~ does the mobile pass through the coordinate point $x = 3 \text{ cm}$ x_m for the first time is:

$$\text{at } t = t_1 \begin{cases} x = 3 \cos(2.5\pi t_1 - \frac{\pi}{2}) = 3 \text{ cm} \\ -7.5\pi \sin(2.5\pi t_1 - \frac{\pi}{2}) > 0 \end{cases} \quad (v > 0)$$

$$\Rightarrow \begin{cases} \cos(2.5\pi t_1 - \frac{\pi}{2}) = 1 \\ \sin(2.5\pi t_1 - \frac{\pi}{2}) < 0 \end{cases} \Rightarrow 2.5\pi t_1 - \frac{\pi}{2} = 0 + 2k\pi$$

$$\Rightarrow 2.5 \cancel{\pi} t_1 - \frac{\pi}{2} = 0 + 2k\cancel{\pi}$$

$$\text{for } k=0 \Rightarrow 2.5 t_1 = \frac{1}{2} + 2k \overset{0}{\cancel{\pi}}$$

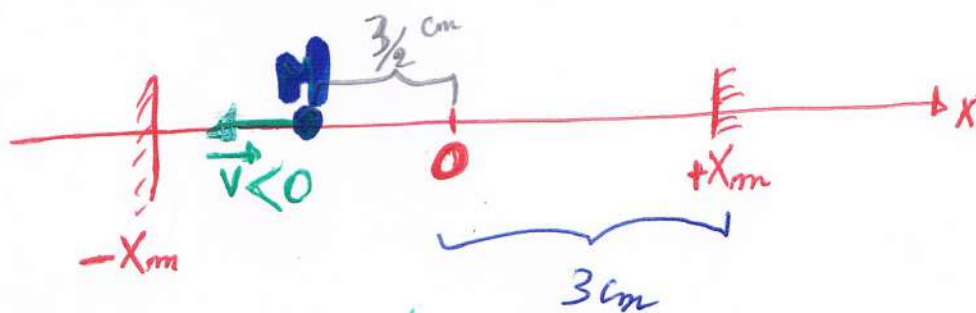
$$\text{for } k=0 \Rightarrow 2.5 t_1 = \frac{1}{2} \Rightarrow \boxed{t_1 = 0.2 \text{ s}}$$

→ Velocity at this date ($t_1 = 0.2 \text{ s}$) and $x = x_m = 3 \text{ cm}$

$$V = - \overset{\text{cm}}{3 \times 10^2} (2.5\pi) \sin \underbrace{(2.5\pi (0.2) - \frac{\pi}{2})}_{0//}$$

$$\boxed{V = 0 \text{ (m/s)}} \text{ at } t_1 = 0.2 \text{ s and } x = x_m = 3 \text{ cm}$$

3/ the time t_2 ? the moving mobile passes through the coordinate point $x = \frac{3}{2} \text{ cm}$ for the first time in the negative direction $V < 0$



$$\text{at } t = t_2 \Rightarrow \begin{cases} x(t) = \overset{\text{cm}}{3} \cos(2.5\pi t_2 - \frac{\pi}{2}) = \overset{\text{cm}}{\frac{3}{2}} \\ V(t) = -7.5\pi \sin(2.5\pi t_2 - \frac{\pi}{2}) < 0 \end{cases}$$

$$\Rightarrow \begin{cases} \cos(2.5\pi t_2 - \frac{\pi}{2}) = \frac{1}{2} \\ \sin(2.5\pi t_2 - \frac{\pi}{2}) > 0 \end{cases}$$

$$\Rightarrow \begin{cases} \cos(2.5\pi t_2 - \frac{\pi}{2}) = \frac{1}{2} \\ \sin(2.5\pi t_2 - \frac{\pi}{2}) > 0 \end{cases}$$

$$\Rightarrow 2.5\pi t_2 - \frac{\pi}{2} = \frac{\pi}{3} + 2k\pi$$

$$\text{for } k=0 \Rightarrow 2.5 t_2 = +\frac{1}{2} + \frac{1}{3} + 2k$$

$$\text{for } k=0 \Rightarrow 2.5 t_2 = \frac{3+2}{6} = \frac{5}{6}$$

$$\Rightarrow \boxed{t_2 = 0.335}$$

$$\begin{cases} x(t) = 3 \cdot 10^{-2} \cos\left(\underbrace{2.5\pi t}_{\omega = \frac{2\pi}{T}} - \frac{\pi}{2}\right) \text{ [m]} \\ v(t) = -3 \times 10^{-2} (2.5\pi) \sin\left(2.5\pi t - \frac{\pi}{2}\right) \text{ [m/s]} \\ a(t) = -3 \times 10^{-2} (2.5\pi)^2 \cos\left(2.5\pi t - \frac{\pi}{2}\right) \text{ [m/s}^2\text{]} \end{cases}$$

t(s)	0	$\frac{1}{4}$	$\frac{1}{2}$	$\frac{3T}{4}$	T	$\frac{5T}{4}$ (نقطة أخرى)
$\omega t + \phi = \frac{2\pi}{T} t - \frac{\pi}{2}$	$-\frac{\pi}{2}$	0	$\frac{\pi}{2}$	π	$\frac{3\pi}{2}$	
$x(t) = 3 \cos(\omega t + \phi)$	0	+3	0	-3	0	
$v(t) = -7.5\pi \sin(\omega t + \phi)$	+7.5π	0	-7.5π	0	+7.5π	
$a(t) = -18.75\pi^2 \cos(\omega t + \phi)$	0	-18.75π ²	0	+18.75π ²	0	

